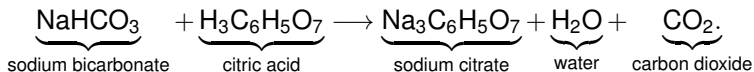


# January 8 Math 3260 sec. 51 Spring 2024

## A Random Motivational Example

Plop plop, fizz fizz, oh what a relief it is<sup>1</sup>.



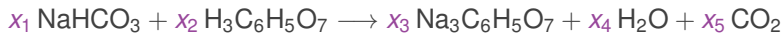
This is an unbalanced chemical equation that describes effervescence of a commercial antacid medication.

**Question:** How many molecules of each substance result in a balanced equation?

---

<sup>1</sup>Sodium bicarbonate and citric acid dissolved in water produces sodium citrate, water, and carbon dioxide.

## Motivating Example: Balancing Atoms



We can introduce a 4-tuple  $\begin{bmatrix} \text{Na} \\ \text{H} \\ \text{C} \\ \text{O} \end{bmatrix}$  and create an equation for the unknowns  $x_1, x_2, x_3, x_4,$  and  $x_5$ .

$$x_1 \begin{bmatrix} 1 \\ 1 \\ 1 \\ 3 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 8 \\ 6 \\ 7 \end{bmatrix} = x_3 \begin{bmatrix} 3 \\ 5 \\ 6 \\ 7 \end{bmatrix} + x_4 \begin{bmatrix} 0 \\ 2 \\ 0 \\ 1 \end{bmatrix} + x_5 \begin{bmatrix} 0 \\ 0 \\ 1 \\ 2 \end{bmatrix}$$

This is an example of the types of equations we want to consider.

## We'll work in a variety of settings...

$$\begin{array}{rclclclclcl} \text{Linear sys.} & x_1 & & & - & 3x_3 & & & = & 0 \\ & x_1 & + & 8x_2 & - & 5x_3 & - & 2x_4 & = & 0 \\ & x_1 & + & 6x_2 & - & 6x_3 & & - & x_5 & = & 0 \\ & 3x_1 & + & 7x_2 & - & 7x_3 & - & x_4 & - & 2x_5 & = & 0 \end{array}$$

$$\text{Matrix eqns.} \quad \begin{bmatrix} 1 & 0 & -3 & 0 & 0 \\ 1 & 8 & -5 & -2 & 0 \\ 1 & 6 & -6 & 0 & -1 \\ 3 & 7 & -7 & -1 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\text{More Matrices} \quad \begin{bmatrix} 1 & 0 & -3 & 0 & 0 & 0 \\ 1 & 8 & -5 & -2 & 0 & 0 \\ 1 & 6 & -6 & 0 & -1 & 0 \\ 3 & 7 & -7 & -1 & -2 & 0 \end{bmatrix}$$

$$\text{Vector eqns.} \quad x_1 \begin{bmatrix} 1 \\ 1 \\ 1 \\ 3 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 8 \\ 6 \\ 7 \end{bmatrix} + x_3 \begin{bmatrix} -3 \\ -5 \\ -6 \\ -7 \end{bmatrix} + x_4 \begin{bmatrix} 0 \\ -2 \\ 0 \\ -1 \end{bmatrix} + x_5 \begin{bmatrix} 0 \\ 0 \\ -1 \\ -2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

## Questions:

- ▶ Is there a set of numbers  $x_1, \dots, x_5$  that satisfy all of the equations?
- ▶ If there is a set of numbers, is it the only one?
- ▶ Are there simple algorithms we can use to answer these questions?

These are some of the questions addressed by Linear Algebra. We'll also consider two main abstractions:

## Vector Spaces and Linear Transformations.

## Section 1.1: Systems of Linear Equations

We begin with a linear (*algebraic*) equation in  $n$  *real* variables  $x_1, x_2, \dots, x_n$  for some positive integer  $n$ .

### Definition

A **linear equation** in the variables  $x_1, \dots, x_n$  is one that can be written in the form

$$a_1x_1 + a_2x_2 + \cdots + a_nx_n = b,$$

where  $a_1, \dots, a_n$  are real (or complex) constants called the *coefficients*, and  $b$  is a constant.

In general, the coefficients and the right hand side  $b$  are known.

# Linear Equation in $n$ Variables

$$a_1x_1 + a_2x_2 + \cdots + a_nx_n = b.$$

Notice the main structure on the left side. The unknowns/variables ( $x_1, \dots, x_n$ ) are

- ▶ multiplied by numbers (a.k.a. coefficients), and
- ▶ added together.

Other types of actions (squaring, multiplying variables, taking variable's reciprocal, etc.) aren't allowed if an equation is **linear**.

## Examples of Equations that are or are not Linear

$$2x_1 = 4x_2 - 3x_3 + 5 \quad \text{and} \quad 12 - \sqrt{3}(x + y) = 0$$

These equations are linear.

$$2x_1 - 4x_2 + 3x_3 = 5$$

$$\sqrt{3}x + \sqrt{3}y = 12$$

Note that both can be written in the format from the definition. The only operations on the variables are (1) multiply by constants and (2) add.

## Examples of Equations that are or are not Linear

$$x_1 + 3x_3 = \frac{1}{x_2} \quad \text{and} \quad xyz = \sqrt{w}$$

These equations are NOT linear.

Reciprocals are not linear

The product  $xyz$  is non-linear  
as is  $\sqrt{w}$ .



## Definition

A **linear system** (or linear system of equations) is a collection of linear equations in the same variables.

The equations in a linear system are considered together as one *object*.

Example 1:

$$\begin{array}{rcccccccl} 2x_1 & + & x_2 & - & 3x_3 & + & x_4 & = & -3 \\ -x_1 & + & 3x_2 & + & 4x_3 & - & 2x_4 & = & 8 \end{array}$$

Example 1 is a linear system that has two equations in four variables.

Example 2:

$$\begin{array}{rcccccccl} & & x & + & 2y & + & 3z & = & 4 \\ & 3x & & & & + & 12z & = & 0 \\ & 2x & + & 2y & - & 5z & = & -6 \end{array}$$

Example 2 is a linear system that has three equations in three variables.

In this course, we'll mostly use a single variable name with subscripts, i.e.,  $x_1, x_2, x_3$  as opposed to  $x, y, z$ .

# Some Preliminary Terms

Consider the system of  $m$  equations in the variables  $x_1, \dots, x_n$

$$\begin{array}{ccccccccc} a_{11}x_1 & + & a_{12}x_2 & + & \cdots & + & a_{1n}x_n & = & b_1 \\ a_{21}x_1 & + & a_{22}x_2 & + & \cdots & + & a_{2n}x_n & = & b_2 \\ & & \vdots & & \vdots & & \vdots & = & \vdots \\ a_{m1}x_1 & + & a_{m2}x_2 & + & \cdots & + & a_{mn}x_n & = & b_m. \end{array} \tag{1}$$

## Definitions: Solution and Solution Set

A **solution** of (1) is an ordered list of numbers  $(s_1, s_2, \dots, s_n)$  that reduce each equation in the system to a true statement upon substitution<sup>a</sup>.

The **solutions set** of (1) is the set of all possible solutions.

---

<sup>a</sup>It is assumed that substitution means setting  $x_1 = s_1, x_2 = s_2$  and so forth.

## Some Preliminary Terms

Consider the system of  $m$  equations in the variables  $x_1, \dots, x_n$

$$\begin{array}{ccccccccc} a_{11}x_1 & + & a_{12}x_2 & + & \cdots & + & a_{1n}x_n & = & b_1 \\ a_{21}x_1 & + & a_{22}x_2 & + & \cdots & + & a_{2n}x_n & = & b_2 \\ & & \vdots & & \vdots & & \vdots & = & \vdots \\ a_{m1}x_1 & + & a_{m2}x_2 & + & \cdots & + & a_{mn}x_n & = & b_m. \end{array}$$

### Definition: Equivalent Systems

Two linear systems are called **equivalent** (or equivalent systems) if they have the same solution set.

**Remark:** We'll often use some process to rewrite a system in terms of an equivalent system for which the solution(s) is more obvious.

## An Example

$$\begin{aligned}2x_1 - x_2 &= -1 \\ -4x_1 + 2x_2 &= 2\end{aligned}$$

(a) Show that  $(1, 3)$  is a solution.

Set  $x_1 = 1$  and  $x_2 = 3$

$$\begin{aligned}2(1) - (3) &\stackrel{?}{=} -1 \\ 2 - 3 &= -1\end{aligned}$$

it's true

$$\begin{aligned}-4(1) + 2(3) &\stackrel{?}{=} 2 \\ -4 + 6 &= 2\end{aligned}$$

it's also true.

## An Example Continued

$$\begin{array}{rclcrcl} 2x_1 & - & x_2 & = & -1 \\ -4x_1 & + & 2x_2 & = & 2 \end{array}$$

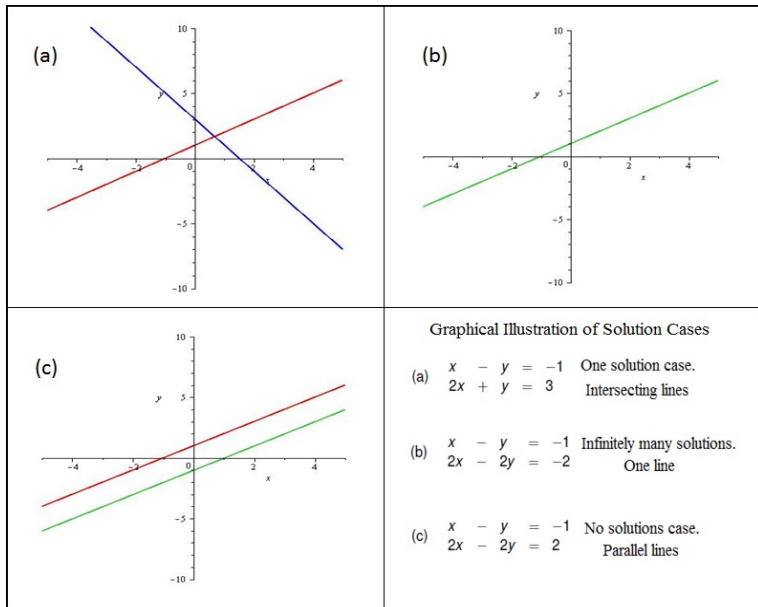
(b) The **solution set** for this system is

$$\left\{ (x_1, x_2) \mid x_1 = -\frac{1}{2} + \frac{1}{2}x_2 \right\}.$$

Notice that setting  $x_1 = -\frac{1}{2} + \frac{1}{2}x_2$  in each equation we get the pair of true statements

$$\begin{array}{rclcrcl} 2\left(-\frac{1}{2} + \frac{1}{2}x_2\right) & - & x_2 & = & -1, & \text{and} \\ -4\left(-\frac{1}{2} + \frac{1}{2}x_2\right) & + & 2x_2 & = & 2. \end{array}$$

# The Geometry of 2 Equations with 2 Variables



# Theorem

## Theorem

For a linear system, exactly one of the following holds. The system has

- i no solution, or
- ii exactly one solution, or
- iii infinitely many solutions.

A system is called **inconsistent** if it does not have any solutions (case i), and it's called **consistent** if it has any solution(s) (cases ii & iii).

**Note:** This theorem speaks to those two big questions:

- ▶ Existence: Is there a solution/does a solution exist?
- ▶ Uniqueness: Is there a unique solution or multiple solutions?